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Research Paper

A pilot study of aortic hemodynamics before and after thoracic endovascular repair with a double-branched endograft



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ABSTRACT

Branched endografts have been developed to treat complex pathology in the aortic arch and ascending aorta. This study aims to evaluate the haemodynamic performance of a double-branched thoracic endograft by detailed comparison of flow patterns and wall shear stress in the aorta and supra-aortic branches before and after stentgraft implantation. Pre- and post-intervention CT images were acquired from two patients who underwent thoracic endovascular aortic repair (TEVAR) with a double-branched endograft for thoracic aortic aneurysms. These images were used to reconstruct patient-specific models, which were analysed using computational fluid dynamics employing physiologically realistic boundary conditions. Our results showed that there was sufficient blood perfusion through the arch branches. The presence of inner tunnels caused flow derangement and asymmetric wall shear stress in the ascending aorta, where shear range index was up to 6 times higher than in the preintervention model. Wall shear stress in the aortic arch increased considerably after intervention as a result of accelerated flow. The maximum flow-induced displacement forces on the branched endografts were around 22 N for both patients, which was below the threshold for device migration. Results from this pilot study demonstrated that aortic flow patterns were significantly altered by the branched endograft which caused increased spatial variation of wall shear stress in the ascending aorta and the arch. Although no obvious adverse hemodynamic features were found immediately after intervention for the cases we analysed, follow-up studies will be needed to assess durability of the device.

1. Introduction

Thoracic endovascular aortic repair (TEVAR) has been developed over 2 decades and has become one of the most popular choices for treating descending thoracic aortic diseases. In recent years, its application has been extended more proximally in the aorta, if there is a suitable landing zone, to treat pathology in the aortic arch and ascending aorta. However, traditional stent-grafts are too stiff to conform to the inner curvature of the aortic arch, which may result in a wedge-shaped gap between the aortic wall and the under surface of the graft, known as birdbeak configuration [1]. To overcome this challenge, branched endografts have been developed, including single-branched and multi-branched endografts. One such example is the Relay thoracic stent-graft system developed by Bolton Medical (Sunrise, FL, US), which was designed to conform into the tight aortic curvature in order to avoid the bird-beak configuration [2].

It is well recognised that blood flow in aortic aneurysms is highly

disturbed, with the presence of flow recirculation and strong vortices [3, 4]. Insertion of a branched stent-graft may further increase the complexity of the flow [5]. In order to provide a non-invasive evaluation of aortic flow patterns, computational fluid dynamics (CFD) has been employed for its ability to offer comprehensive insights into spatial-temporal variations of the flow [6]. When applied to patient-specific aorta geometry reconstructed from medical images together with physiological boundary conditions, CFD allows quantitative assessment of cardiovascular flow with good accuracy [7–9].

Computational studies have been conducted on blood flow in the human aortic arch, where geometrical complexities such as tortuosity, non-planarity and the presence of supra-aortic branches are included to understand their effects on blood flow [10,11]. CFD simulations have also been performed to investigate the role of blood flow patterns and hemodynamic parameters in pathological changes of the aorta [12–14]. In addition, fluid-structure interaction (FSI) simulations have been performed on the aortic arch with and without an aneurysm [15–17]. Most

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recently, Miyazaki et al. [18] applied different turbulence models to evaluate the effect of turbulence on blood flow in the aortic arch by comparing 4D flow magnetic resonance imaging (MRI) measurements with CFD simulation results. While most of previous computational studies focused on flow in normal and diseased aortic arch, only a few considered the influence of endografts [1,19–22]. Nardi et al. [19], among others, compared the hemodynamic performance of different endovascular procedures for the treatment of aortic arch aneurysm using idealised geometric models. Van Bogerijen et al. [1] employed patient-specific models to examine the effect of TEVAR with a focus on the bird-beak configuration. Patient-specific analysis of flow in double-branched aortic arch endograft has not been reported in the literature.

Detailed knowledge of the hemodynamic performance of doublebranched thoracic endografts is important for assessing the risk of postintervention complications and long-term durability of the device. The most common and potentially life-threatening post-TEVAR complications include endoleaks, distal migration of the device, and thrombus formation within the stent-graft. Among all types of endoleaks, type I endoleaks occur more frequently in TEVAR, resulting from poor sealing between the device and the aortic wall [23]. Distal migration of the device can also result in type I endoleak, thereby increasing the risk of aneurysm rupture. Thrombus formation within the stent-graft can reduce or even block blood perfusion to the supra aortic branches, which may lead to ischaemia. All these complications are associated with abnormal flow behaviour and flow induced forces. For example, high values of shear stress may cause platelet activation, whereas low wall shear stress and long residence time can promote platelet adhesion and thrombus formation [24,25]. Large displacement forces acting on the stent-graft are the main cause for device migration [26]. However, these flow-related parameters could not be measured directly in vivo. Through this pilot study we aim to provide the first detailed evaluation of the hemodynamic performance of double-branched thoracic endografts by means of patient-specific CFD analysis. Pre- and post-intervention geometries were reconstructed from the CT images acquired before and after the TEVAR procedure. These were then coupled with physiologically realistic boundary conditions. Hemodynamic performance was evaluated in terms of flow pattern, wall shear stress (WSS) related indices and displacement forces (DF). By comparing pre- and post-intervention flow distributions, it would be possible to assess the level of blood perfusion through the arch branches. Quantitative analysis of WSS-related indices would help predict the likelihood of thrombus formation within the endograft, whilst quantification of DF experienced by the endograft would allow us to evaluate the risk of device migration.

2. Methods

2.1. Branched stent-graft and CT scan

The studied branched device (Bolton Medical, Sunrise, FL, US) comprises a main covered stent-graft to take the pressure off the vessel wall of the aortic arch and two attached tunnels to channel the blood directly into the innominate artery (IA) and left common carotid artery (LCCA). Patient 1 was treated with an endograft with 2 inner branches of equal diameters (15 mm) while the inner branch to the LCCA of patient 2 had a smaller diameter (9 mm) compared to the IA (17 mm). For both patients, the left subclavian artery (LSCA) was covered at the root, and a separate bypass procedure was performed to supply blood to the LSCA from the LCCA. CT images for both patients were acquired (1.25 mm slice thickness and 0.675 mm/pixel in-plane resolution) with a Discovery CT750 HD scanner (GE Healthcare, Chicago, IL, US), at voltages of 100 KV and 120 KV, for the pre- and post-intervention scans, respectively. Formal ethical approval was not required for this limited retrospective and anonymised study.

2.2. Model geometry

The multislice transverse images were processed using image analysis software MIMICS 20.0 (Materialise, Leuven, Belgium), with luminal surface being segmented based on the local signal intensity. The segmented 2D masks were then smoothed by the Discrete Gaussian filter based on a linear smoothing enhancement algorithm. 3D reconstruction was performed through surface rendering, which involved delineating lumen contours for each slice in the transverse plane and generating a 3D surface by superimposing and lofting these contours in the coronal plane. Finally, a cubic spline algorithm was applied for 3D smoothing. The representative CT images and reconstructed luminal surfaces of the preand post-intervention models are presented in Fig. 1. In the reconstructed models, the presence of stent wires was ignored and the inner surface of the stent-graft was assumed to be smooth. Blooming artefacts due to the presence of thin stent wires were not a major concern here as the stent mesh was not very dense and the lumen diameter is fairly large.

The 3D geometries were then imported into ANSYS ICEM CFD (ANSYS, Canonsburg, PA, US) to generate computational mesh, which consisted of tetrahedral elements in the core region and locally refined hexahedral elements in the sheared boundary layer for accurate prediction of hemodynamic wall parameters. The viscous sub-layer (approximately 1 mm thick) was divided into a minimum of 10 prismatic elements to ensure that the dimensionless height of the near wall elements, y+, was less than 1. Mesh sensitivity tests were carried out, starting with a mesh containing approximately 1 million elements. The final adopted meshes consisted of around 3 and 8.5 million elements for the pre- and post-intervention aortas, respectively. Results were considered to be grid independent when differences in velocity and WSS were less than 2% between the adopted mesh and a finer mesh. A fixed timestep of 0.001s was chosen based on a similar sensitivity test on timestep size.

2.3. Flow model

The conservation of mass and momentum equations for an incompressible, Newtonian fluid were used to describe the pulsatile blood flow. In addition, the hybrid k- ε /k- ω correlation-based shear stress transport transitional model (SST-Tran) was applied to capture transitional/turbulent flow characteristics [27]. Blood was assumed to have a constant density of 1060 kg/m³ and dynamic viscosity of 4 mPa s.

2.4. Boundary conditions

Physiological boundary conditions were employed in order to produce clinically relevant results. Since patient-specific flow information was not available, velocity waveform acquired from a patient with thoracic aortic aneurysm was adopted [16] and scaled according to the inlet area of each patient, yielding a cycle-averaged inlet velocity of 0.1 m/s for both patients. This corresponds to a cardiac output of 5 L/min for patient 1 and 3.4 L/min for patient 2, both are within the physiological range [28]. A schematic of the computational model and the applied inflow waveform can be found in Fig. 2.

At each model outlet, a 3-element Windkessel model (3-EWM) was applied in order to provide physiological outflow boundary conditions. The 3-EWM describes an arterial system by using arterial compliance (C), proximal impedance of the aorta (R1) and peripheral resistance (R2). It is capable of capturing the main characteristics of arterial blood pressure waveform [29]. The assumption of rigid stent-graft walls was made where no-slip boundary conditions were imposed. To calculate the 3-EWM parameters, pressure waveforms at each outlet were adopted from the literature [30] and the corresponding cycle-averaged pressures were evaluated as: 105 mmHg, 104 mmHg, 103 mmHg, and 103 mmHg, for the IA, LCCA, LSCA and descending aorta (DA), respectively. For the post-intervention model, the outlet boundary conditions were modified to account for the fact that the LSCA was covered at the root and its blood

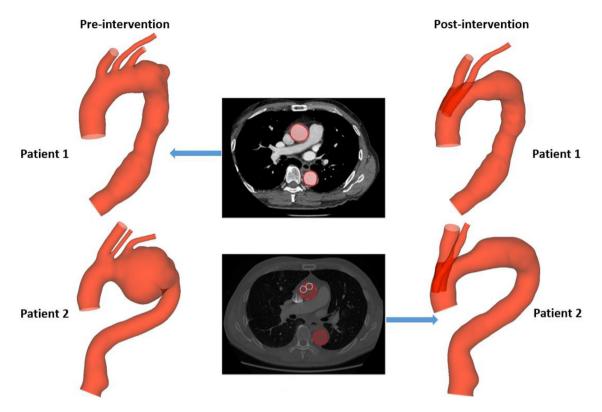


Fig. 1. Two patient-specific models reconstructed from pre- and post-intervention CT images.

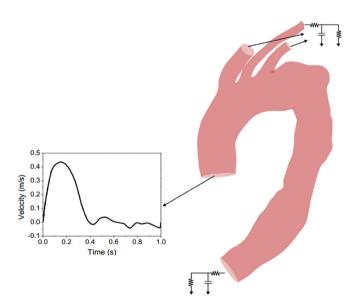
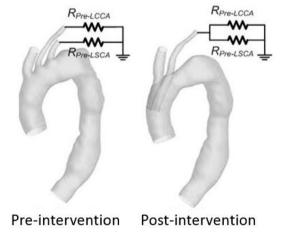


Fig. 2. Schematic of the computational model employed in this study. Velocity waveform was prescribed at the inlet, while a 3-element Windkessel model was applied at all outlets.

supply was rerouted from the LCCA via a separate bypass procedure. As shown in Fig. 3, the total downstream resistance at the LCCA outlet was calculated by combining the pre-intervention resistance for the LCCA ($R_{Pre-LCCA}$) and LSCA ($R_{Pre-LSCA}$) [31]:

$$^{1}/_{R_{Post-LCCA}} = ^{1}/_{R_{Pre-LCCA}} + ^{1}/_{R_{Pre-LSCA}}$$

The obtained resistance and compliance values are summarised in Table 1.



 $\textbf{Fig. 3.} \ \ \textbf{Schematic diagram showing resistance at LCCA} \ \textbf{and LSCA} \ \textbf{in the pre-and post-intervention models}.$

2.5. Computational details

The governing equations were solved by means of ANSYS CFX 15 (ANSYS, Canonsburg, PA, US), which is a finite volume based CFD code. Spatial and temporal discretisations were performed by adopting the second order accurate advection scheme and the second order implicit backward Euler scheme, respectively. Convergence of simulations was controlled by setting the residual tolerance as 1×10^{-5} . Each simulation was performed for three cardiac cycles when solutions for both velocity and pressure became periodic, and the differences in systolic pressure between the second and third cardiac cycle were less than 2% at every outlet. Three cardiac cycles are usually considered sufficient to achieve a periodic solution as demonstrated in similar studies [5,8,26,32]. Numerical results of the last cycle were analysed using ANSYS CFD-Post 15

 Table 1

 Windkessel parameters for all model outlets.

| | | Patient 1 | | | Patient 2 | | | |
|-------------------|------|---|---|--|---|---|--|--|
| | | R1 [10 ⁸ Pa s m ⁻³] | R2 [10 ⁸ Pa s m ⁻³] | C [10 ⁻⁹ m ³ Pa ⁻¹] | R1 [10 ⁸ Pa s m ⁻³] | R2 [10 ⁸ Pa s m ⁻³] | C [10 ⁻⁹ m ³ Pa ⁻¹] | |
| Pre-intervention | IA | 0.40 | 8.94 | 1.92 | 0.39 | 10.86 | 1.59 | |
| | LCCA | 1.86 | 31.51 | 0.54 | 3.92 | 79.01 | 0.22 | |
| | LSCA | 1.23 | 22.32 | 0.76 | 2.30 | 50.00 | 0.34 | |
| | DA | 0.08 | 2.27 | 7.62 | 0.07 | 3.43 | 5.11 | |
| Post-intervention | IA | 0.49 | 8.86 | 1.92 | 0.26 | 10.99 | 1.59 | |
| | LCCA | 2.21 | 11.60 | 1.30 | 2.73 | 29.34 | 0.56 | |
| | DA | 0.08 | 2.27 | 7.62 | 0.07 | 3.43 | 5.11 | |

(ANSYS, Canonsburg, PA, US) and CEI Ensight 10 (CEI Inc, Apex, NC, US).

2.6. Hemodynamic indices

Wall shear stress (WSS) refers to the tangential force generated by blood flow on the endothelial luminal surface. Owing to its strong associations with thrombus formation and aneurysm growth and the fact that these processes are much slower compared to the pulsatile cycle period, WSS is usually evaluated in terms of time-averaged wall shear stress (TAWSS), defined as

$$TAWSS = \frac{1}{T} \int_0^T WSS \cdot dt \tag{1}$$

where T is the duration of a cardiac cycle, and t is time. In addition, circumferential wall shear stress (CWSS) and shear range index (SRI) were evaluated to quantify the extent of local derangement at the vessel wall [33].

$$SRI = \frac{\max[CWSS_{max}(\theta, t) - CWSS_{min}(\theta, t)]}{TACWSS}$$
 (2)

where CWSS_{max} (θ, t) and $\text{CWSS}_{\text{min}}(\theta, t)$ represent the maximum and minimum WSS along the circumference of a cross-section, respectively. TACWSS is the temporal and circumferential averaged WSS at a given cross-section

The displacement force was calculated by integrating pressure and WSS over the entire surface of the endograft. It is defined as [26]:

$$F_{d,i} = \int_{A_i}^{1} p \ dA + \int_{A_i}^{1} \left(-\mu \frac{\partial \overrightarrow{v_t}}{\partial \widehat{n}} \right) \ dA$$
 (3)

where the first term represents the pressure force and the second term represents the WSS force. A is the area of the endograft wall, and i refers to x, y and z in Cartesian coordinates. $\overrightarrow{v_t}$ is the tangential velocity with respect to the unit normal \widehat{n} for each wall element and μ is the blood viscosity. The magnitude of displacement force F_d is given by:

$$|F_d| = \sqrt{(F_{d,x})^2 + (F_{d,y})^2 + (F_{d,z})^2}$$
 (4)

3. Results

3.1. Anatomical features

As shown in Fig. 1, the pre- and post-intervention geometries differed mainly in the arch for both patients. In the post-intervention model, two built-in tunnels were attached to the main graft body, through which separate stents were retrogradely inserted into the IA and LCCA, with entry to the LSCA being blocked from its origin. Lumen diameters were measured at eight selected locations to evaluate changes in aorta morphology after the intervention, and the results are summarised in Table 2. All locations were matched between the pre- and post-intervention geometries by measuring the distance along the respective centreline, which could be achieved in Mimics.

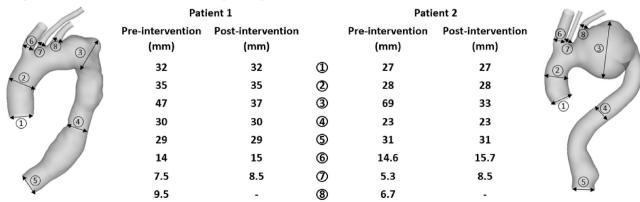
Comparisons showed that, apart from the obvious reduction in diameters in the regions where the aneurysms were located, there was no change in the ascending and descending aortas for both patients. Diameters of the IA and LCCA root were larger after intervention, with patient 2 showing a more pronounced increase in LCCA diameter.

3.1.1. Flow patterns

Instantaneous velocity streamlines in the pre- and post-intervention models were compared at three characteristic time points, namely, peak systole (0.15 s), mid-systolic deceleration (0.29 s) and diastole (0.74 s). As shown in Fig. 4a&b, aortic flow patterns for both patients altered significantly after intervention in response to changes in lumen morphology. Blood flow was more organised post-intervention as the

 Table 2

 Comparison of lumen diameters (mm) between the pre- and post-intervention models.



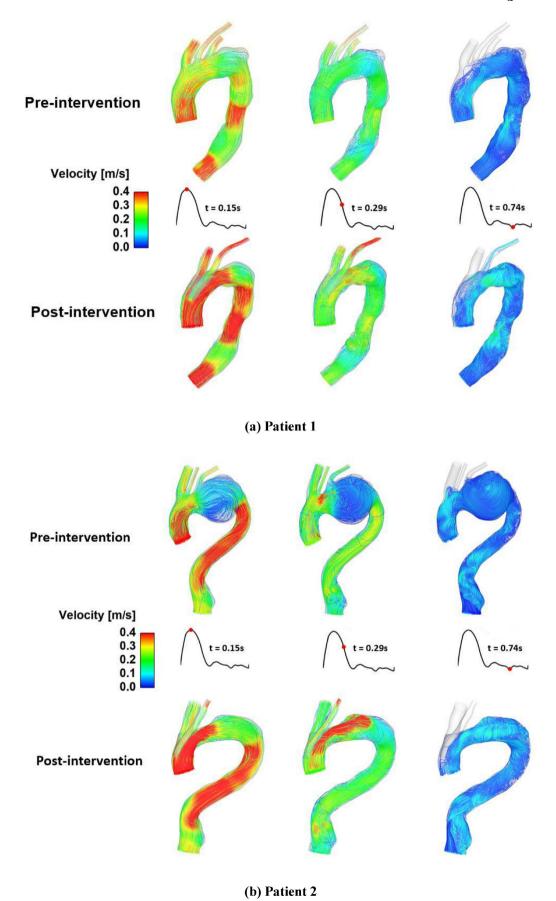


Fig. 4. Comparisons of instantaneous velocity streamline in pre- and post-intervention models of (a) patient 1 and (b) patient 2.

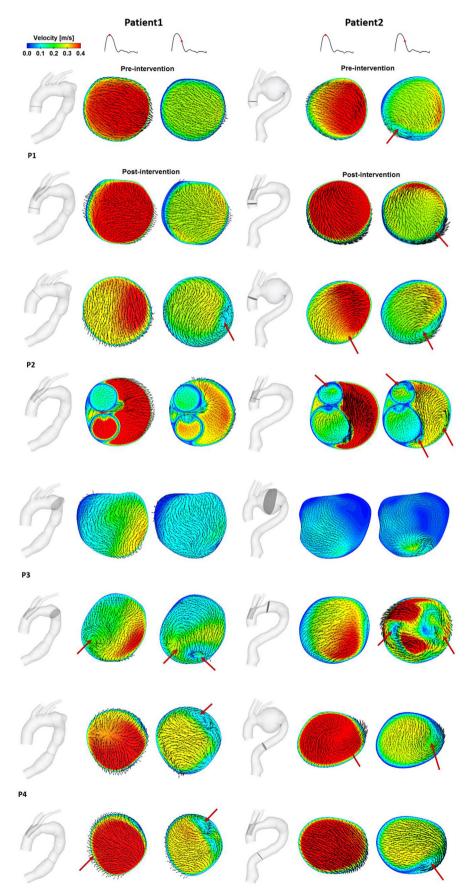


Fig. 5. a. Comparison of axial velocity contours along with in-plane velocity vectors before and after intervention in the main aortas of patient 1 (left) and patient 2 (right). b. Comparison of axial velocity contours along with in-plane velocity vectors before and after intervention in the IA of patient 1 (left) and patient 2 (right). c. Comparison of axial velocity contours along with in-plane velocity vectors before and after intervention in the LCCA of patient 1 (left) and patient 2 (right).

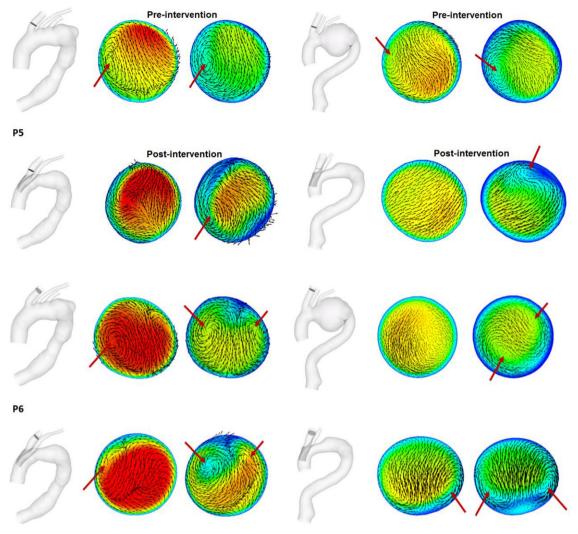


Fig. 5. (continued).

aneurysm was repaired. Blood velocities increased in the ascending aorta and the arch due to the presence of the inner tunnels. Flow in the LCCA increased in order to meet the demand of both LCCA and LSCA. As expected, the diastolic phase was dominated by slow and recirculating flow in both pre- and post-intervention aortas.

Eight cross-sectional planes were selected along the centreline of each aorta (P1-P4), the IA (P5 & P6) and the LCCA (P7 & P8) for detailed comparisons of flow and WSS. Through-plane velocity contours along with in-plane velocity vectors at these planes were compared before and after intervention, as illustrated in Fig. 5a-c, where the right hand side of each cross-sectional image corresponds to the inner curvature of the aorta and vortical flow structures are indicated by red arrows. For both patients, flow in the proximal ascending aorta (P1) hardly changed after the intervention, but this was completely different at P2 where the presence of the inner tunnels caused part of the aortic flow to be channelled into the IA and LCCA after intervention, while entry to the LSCA was blocked. Insertion of the stent-graft reduced the lumen area and thus accelerated blood flow in the posterior region but blocked flow in the anterior part. This stagnant region is likely to be thrombosed over time which may further obstruct the lumen. It can be seen clearly at P2 that patient 1 had a device with equal diameter inner tunnels, while patient 2 had a smaller inner branch to the LCCA. Patient 1 had a much higher blood velocity in the inner IA channel than LCCA when compared to patient 2. Geometric variations in the aneurysm sac (P3) changed local flow patterns after intervention, where vortical flow could be seen in

systole. Flow in the descending aorta (P4) was similar before and after intervention.

Flow patterns in the arch branches were compared at two locations: (1) proximal region of the IA (P5) and LCCA (P7); and (2) distal region of the IA (P6) and LCCA (P8). It can be seen that velocity was higher in the IA than LCCA in the pre-intervention models of both patients, but more obvious for patient 1. These were the same for the post–intervention models, but only in the proximal regions (P5, P7). For both patients, blood flow in the LCCA (P7, P8) accelerated distally due to vessel tapering. The effect of tapering was more obvious in the LCCA than in IA.

3.2. Wall shear stress

Fig. 6 shows the predicted TAWSS contours, and it is clear that after intervention the magnitude of TAWSS increased throughout the aorta for both patients, as a result of accelerated flow in the arch and the distal LCCA. More detailed comparisons are shown in Fig. 7, where the mean circumferential WSS was plotted as a function of time at the pre-defined locations (P1–P8). For both patients, although temporal variations of circumferential WSS exhibited similar shapes before and after intervention, implantation of the branched stent-graft increased the magnitude of WSS in the systolic phase except for the proximal LCCA (P7) of patient 2, where higher WSS was found in the pre-intervention model. In diastole, however, the results were comparable except for P3 of both patients, where the post-intervention WSS was higher throughout the cardiac

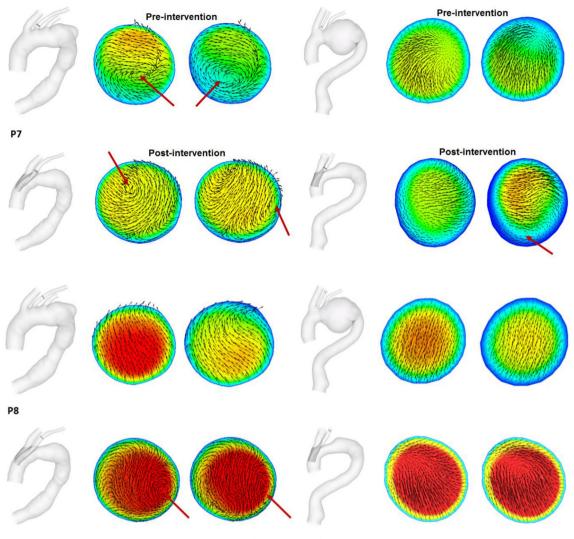


Fig. 5. (continued).

cycle.

Fig. 8 shows the circumferential WSS (CWSS) ranges and their variations during a cardiac cycle, with the maximum range of CWSS being highlighted in red. This range determines the value for SRI, which can be used to quantify the degree of asymmetry in WSS caused by disorganised flow near the arterial wall. For both patients, it was obvious that WSS varied more drastically after intervention with much wider ranges, especially along the main aorta (P1–P4). This was largely attributed to the increased non-uniformity in blood flow caused by the inner tunnels. However, one exception was at P4 of patient 2 where there was little change before and after intervention. WSS ranges also increased in the arch vessels (P5–P8) after intervention except at P7 of patient 2, where WSS was more uniform after intervention.

In order to compare the degree of WSS asymmetry before and after intervention, values for SRI were calculated and the results are summarised in Table 2. For patient 1, it is clear that SRI in the aorta increased significantly after intervention, especially at P2 where SRI was nearly 6 times of its pre-intervention value. However, one exception was in the distal LCCA (P8) where SRI was lower in the post-intervention model. For patient 2, SRI values increased in the ascending aorta and arch vessels after intervention but decreased in the distal arch (P3) and the descending aorta (P4).

3.3. Displacement force

Displacement forces acting on the branched endografts were calculated for both patients and their maximum and cycle-averaged values were 21.91 N and 17.85 N for patient 1 and 21.57 N and 17.86 N for patient 2, respectively. The magnitude of displacement force was dominated by pressure as the effect of WSS was less than 1% in these cases.

4. Discussion

Endovascular treatment of thoracic aortic aneurysms faces great challenges especially when it involves the aortic arch owing to the complex anatomy. The Bolton Medical's Relay device is appealing for complex aortic arch diseases since it is specially designed for the tight aorta curvature. In order to help assess the functionality of this device, a detailed hemodynamic analysis was performed in this study based on patient-specific anatomical data and physiologically realistic boundary conditions [34].

Two patients with thoracic aortic aneurysms were included in this study. Results from the pre- and post-intervention models were analysed so that changes in flow conditions could be determined. In the absence of patient-specific information on blood flow, cycle-averaged volumetric flow rate of 5 L/min and 3.4 L/min were applied at the inlets of patient 1 and patient 2, respectively, with 30% of these leaving the aortic arch through the supra-aortic branches [35]. Flow divisions among the IA,

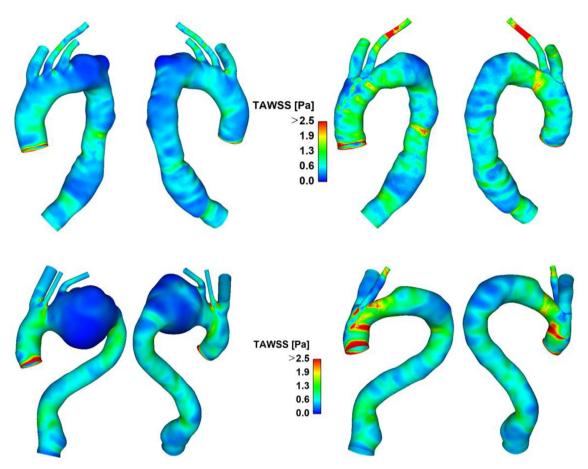


Fig. 6. Comparison of TAWSS before (left) and after (right) intervention for patient 1 (top) and patient 2 (bottom).

LCCA and LSCA were 18%, 5% and 7%, respectively, in the pre-intervention model of patient 1 and 22%, 3% and 5% for patient 2. After intervention, the coverage of LSCA at its root caused flow redistribution, resulting in 0.91 L/min flow through the IA (18%) and 0.62 L/min through the LCCA (12%) of patient 1, while 0.75 L/min through the IA (22%) and 0.27 L/min through the LCCA (8%) of patient 2. For both patients, blood perfusion to the IA was maintained after intervention. The increased flow into the LCCA after intervention was needed as part of it would be diverted into the LSCA through the bypass.

Changes in flow patterns between the pre- and post-intervention models were assessed based on instantaneous velocity streamlines, axial velocity contours and in-plane velocity vectors. As shown in Figs. 4 and 5, the large flow recirculation zone (FRZ) observed in the preintervention aneurysm sacs were absent in the post-intervention models. FRZ is characterized by low velocities and flow reversal, which may favour thrombus formation, leading to partial or complete obstruction of the vessel [5]. Therefore, FRZs should be avoided as much as possible. For both patients, away from the regions covered by the stent-grafts, flow in the proximal ascending aorta and the descending aorta were hardly affected by the intervention. In the supra-aortic branches, blood flow was slightly more uniform in the proximal segments due to the smoother transition from the arch in the post-intervention models. Flow in the LCCA of both patients were increased and locally accelerated flow were more obvious in the distal LCCA, since the distal diameters were smaller compared to the slightly oversized stent-grafts in the proximal regions, which were intended to prevent from device migration.

Owing to increased blood velocities in the distal ascending aorta and the arch, wall shear stress (WSS) in the post-intervention aortas was much higher than in the pre-intervention models for both patients, as can be seen in Figs. 6 and 7 for TAWSS and the mean CWSS, respectively.

WSS is known to influence endothelial cell functions and gene expression, and is associated with vascular remodelling [36-38]. More specifically, low WSS (<0.4 Pa) has been reported to promote thrombus formation and induce intimal thickening. It was noted that patient 1, whose endograft has equal inner tunnel diameters (15 mm), had low TAWSS around the anastomosis between the inner branches and the main stent-graft. These regions are expected to be thrombosed quickly after TEVAR, which would not cause adverse clinical consequences. However, there was a dramatic reduction in TAWSS in the LCCA of patient 2, whose endograft has smaller inner LCCA tunnel (9 mm) than the IA branch (17 mm), which might increase the risk of thrombus formation in this branch. Similar results were reported by van Bakel et al. [22], who computationally compared different endograft designs for zone 0 aortic arch repair, including two designs similar to the device used in this study. By comparing the two designs, they also found that endograft with a smaller LCCA inner tunnel diameter showed higher risk of thrombosis in the supra-aortic vessels, though not significant.

With regards to the circumferential distribution of WSS, which was measured using SRI (Table 3), the post-intervention ascending aortas of both patients showed significantly higher values of SRI, where blood flow were skewed by the presence of inner tunnels. For patient 1, increased SRI values were also observed in the arch, descending aorta and supraaortic branches, except for the distal LCCA where flow was more uniform and accelerated, which led to higher mean CWSS and lower SRI values. In contrast to patient 1, SRI values in the distal arch and descending aorta of patient 2 were reduced after intervention where the mean CWSS values were higher than in the pre-intervention model.

Device migration and future complications, such as type I endoleaks, are associated with pressure and wall shear stress experienced by the stent-graft as blood flows through. It has been suggested that a threshold value of approximately 32 N would be needed to dislocate a non-planar

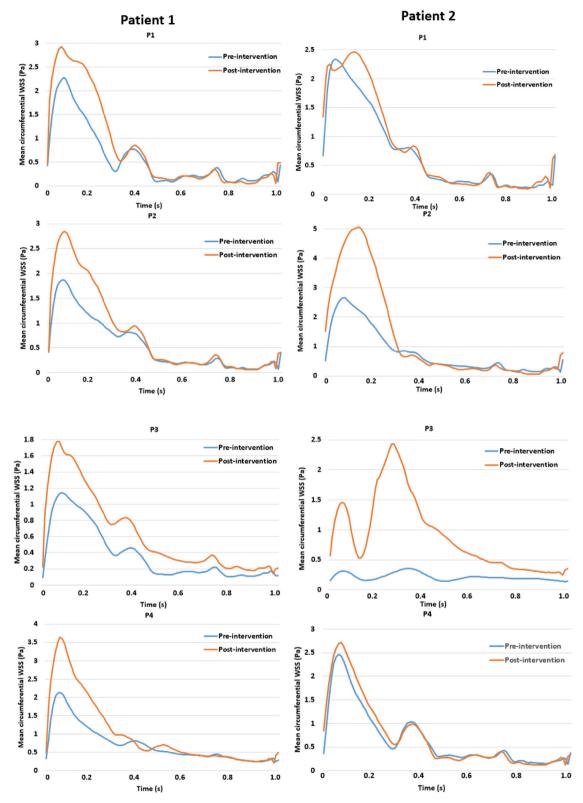


Fig. 7. Comparison of circumferential-averaged wall shear stress (CWSS) at different planes before and after intervention for patient 1 (left) and patient 2 (right).

stent-graft [39], which is well above the maximum displacement forces of 21.91 N and 21.57 N experienced by the branched endografts of patient 1 and patient 2, respectively. Based on these results, it can be deduced that the endografts considered in this study would be at low risk of distal migration.

The present numerical study offered valuable insights into the hemodynamic performance of the branched endograft, but there were some limitations. First, the walls were assumed to be rigid. While this is a reasonable assumption for the relatively stiff endograft, the native aortic wall is compliant and subject to translational motion and radial

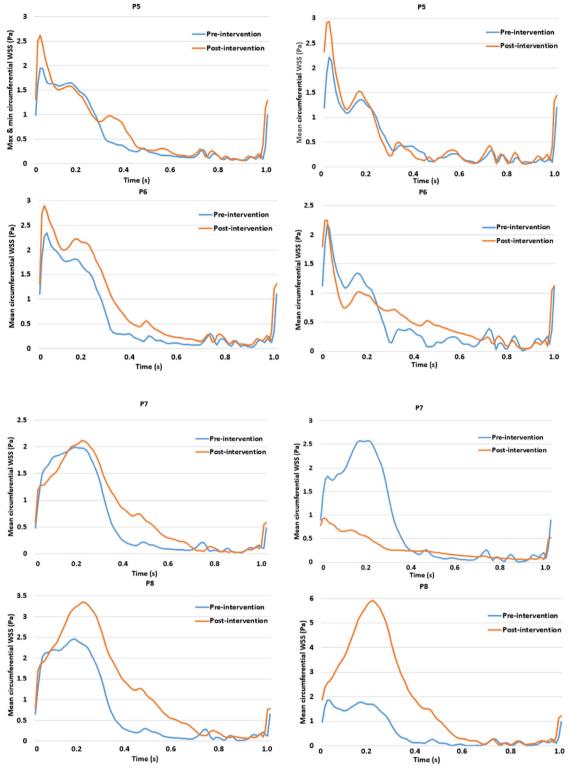


Fig. 7. (continued).

expansion. Second, only two cases were analysed, limiting the wider applicability of the findings. Flow patterns and WSS within the IA and LCCA are expected to be influenced by various factors, including inlet velocity profile in the ascending aorta, length and angles between the branches and the aortic arch. Although the main device features are by and large fixed, future studies of more patient cases will be needed to examine a wide variety of anatomical scenarios. Third, inflow and outflow boundary conditions were based on flow and pressure data

extracted from the literature as patient-specific flow information was not available for this retrospective study. Finally, there was no direct validation of the results as follow-up data of the two patients are not available. Nevertheless, the same computational methods have been adopted in our previous studies, demonstrating a good overall agreement with available in vivo measurements [8,40,41].

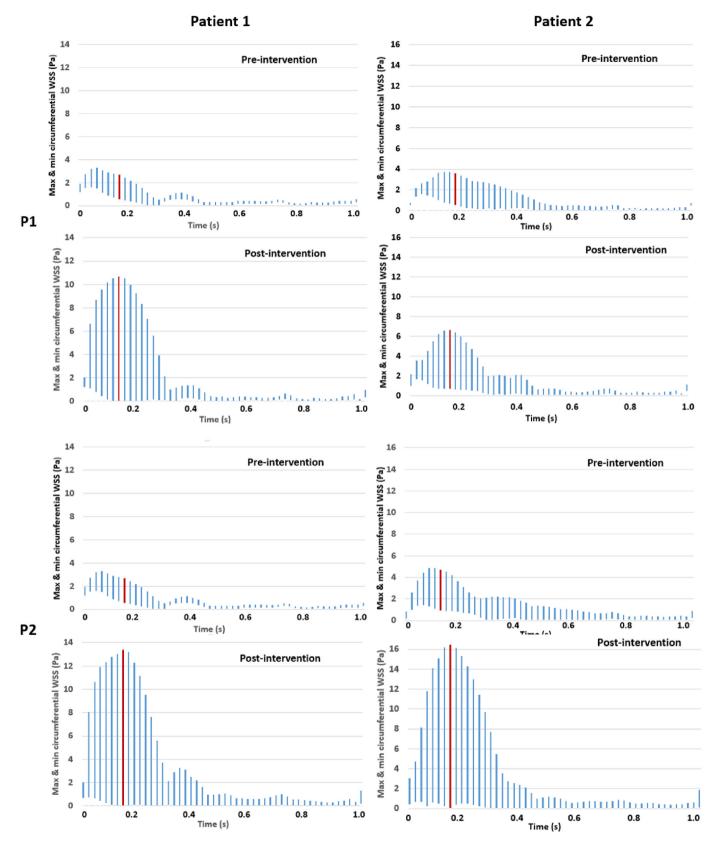


Fig. 8. Comparison of CWSS range in a cardiac cycle before and after intervention for patient 1 (left) and patient 2 (right).

5. Summery

Two thoracic aneurysmal patients were treated with Relay thoracic

endografts and detailed hemodynamic conditions, such as flow patterns and WSS related parameters, were evaluated by means of patient-specific computational simulation. First of all, blood flow to the supra-aortic

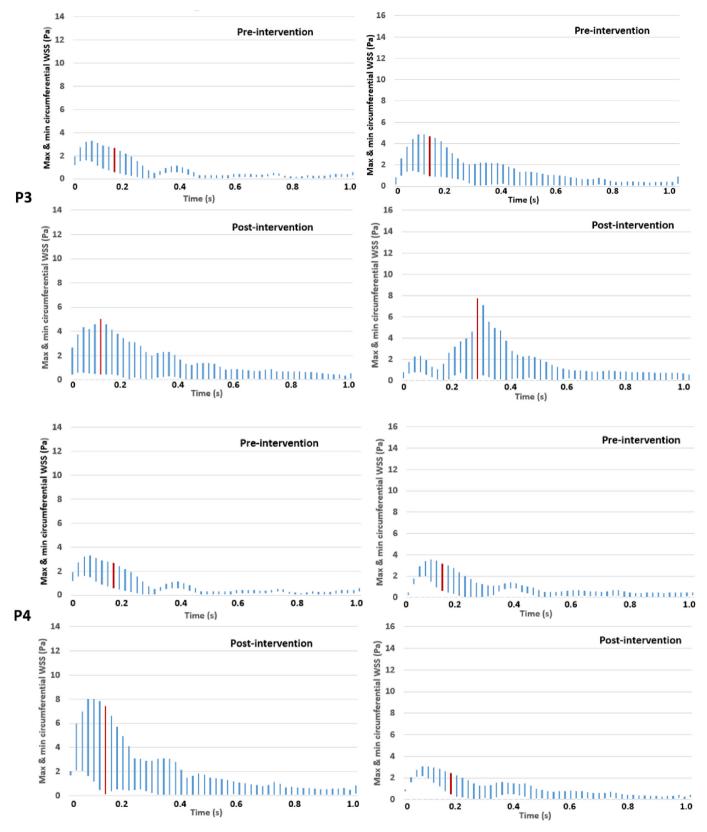


Fig. 8. (continued).

branches was found to be sufficient for both patients. Implantation of the device increased TAWSS in the aortic arch due to accelerated blood flow. Elevated TAWSS may help reduce the risk of thrombus formation, but increased spatial variation of WSS and hemodynamic derangement may

have a detrimental effect in the long term. This highlights the need for clinical and radiological longitudinal follow up. Moreover, the displacement forces experienced by the endografts were evaluated and the values were below the threshold for device migration. Finally,

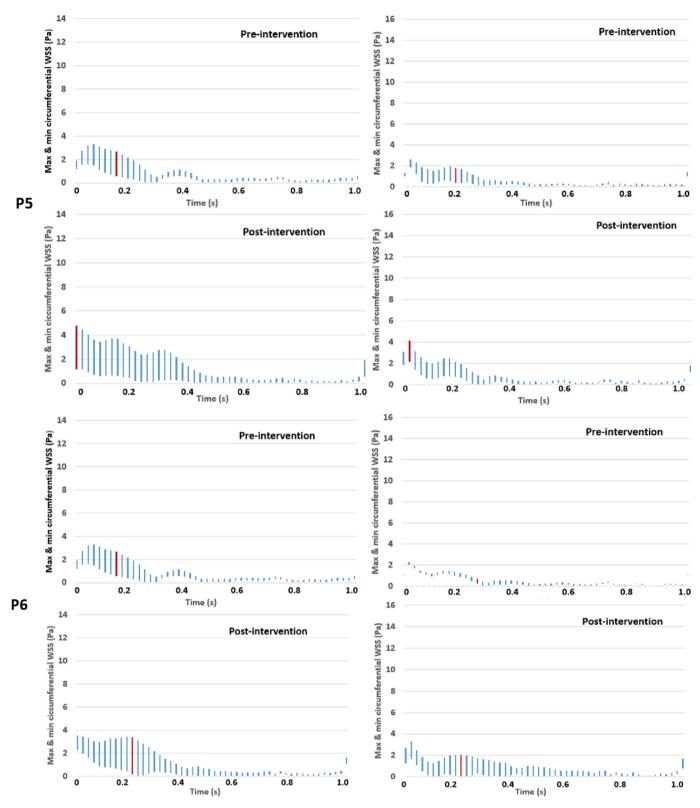


Fig. 8. (continued).

branched endograft with a smaller LCCA inner tunnel diameter may increase the risk of thrombosis in the supra-aortic branch. In conclusion, the overall hemodynamic performance of this novel branched endograft is promising, but more patient-specific cases and follow-up studies will be needed to assess the durability of the device.

Ethical approval

All procedures performed in studies involving human participants were in accordance with the ethical standards of the institutional and/or national research committee and with the 1964 Helsinki declaration and its later amendments or comparable ethical standards.

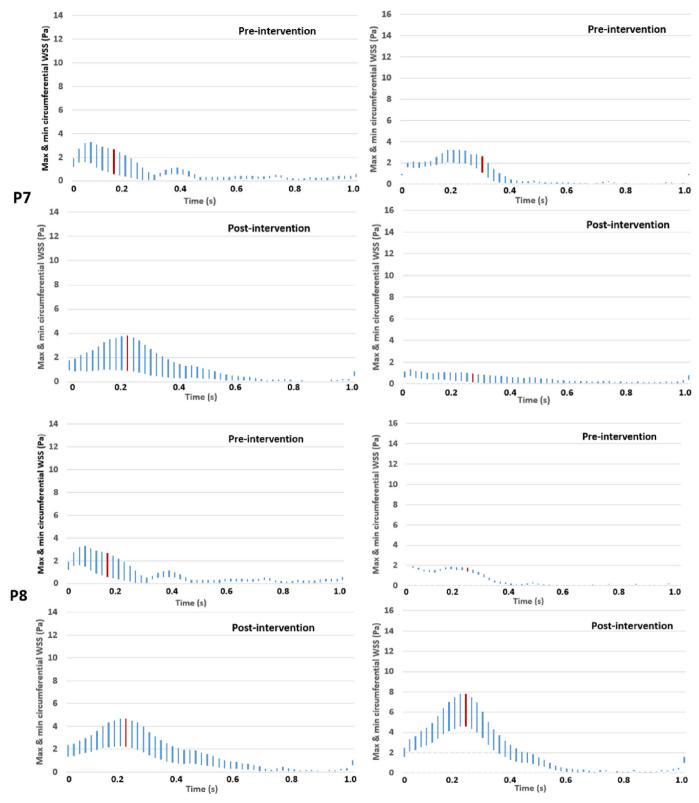


Fig. 8. (continued).

Formal ethical approval was not required for this limited retrospective and anonymised study.

Author contribution

Yu Zhu: Methodology, Software, Validation, Formal analysis,

Writing- Original draft preparation, Visualization. **Wenbo Zhan**: Methodology, Software, Validation, Formal analysis, Writing- Original draft preparation. **Mohamad Hamady**: Conceptualization, Investigation, Writing- Review & Editing, Resources, Funding acquisition. Xiao Yun Xu: Conceptualization, Investigation, Supervision, Writing- Review & Editing, Resources, Funding acquisition.

Table 3Comparison of SRI at different locations before and after intervention for both patients.

| | | P1 | P2 | Р3 | P4 | P5 | P6 | P7 | P8 |
|-----------|-------------------|-------|-------|------|------|------|------|------|------|
| Patient 1 | Pre-intervention | 3.51 | 2.88 | 6.15 | 5.25 | 2.50 | 2.14 | 3.21 | 2.51 |
| | Post-intervention | 12.66 | 16.44 | 7.04 | 7.08 | 5.19 | 3.66 | 3.69 | 1.94 |
| Patient 2 | Pre-intervention | 4.24 | 4.64 | 9.13 | 3.78 | 2.91 | 0.87 | 2.04 | 0.64 |
| | Post-intervention | 7.23 | 12.44 | 8.38 | 2.69 | 3.46 | 3.72 | 2.73 | 1.77 |

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Declaration of competing interest

MH receives honoraria for scientific talks from Vascutek. Other authors have no conflict of interest to declare.

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