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# Knockdown of Slit signalling during limb development leads to a reduction in humerus length

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# 27 Abstract

> Background: Slits (1-3) and their Robo (1-3) receptors play multiple non-neuronal roles in development, including in development of muscle, heart and mammary gland. Previous work has demonstrated expression of *Slit* and *Robo* family members during limb development, where their functions are unclear. Results: In situ hybridisation confirmed strong expression of Slit2, Slit3, Robo1, and Robo2 throughout mouse limb and joint development. No expression of Slit1 or Robo3 was detected. Analysis of Slit1/2 or Slit3 knockout mice revealed normal limb development. In contrast, locally blocking Slit signalling though grafting of cells expressing a dominant-negative Robo2 construct in the proximo-central region of developing chicken limb buds caused significant shortening of the humerus. Conclusions: These findings demonstrate an essential role for Slit/Robo signalling in regulating bone length during chicken limb development.

# 39 Introduction

Secreted Slit ligands bind to Roundabout (Robo) receptors to initiate cell signalling identified initially for its role in regulating axon guidance. Since their discovery in Drosophila, four Robo (Robo 1-4) and three Slit (Slit 1-3) homologs have been identified in vertebrates, although Robo4 is only expressed in endothelial cells.<sup>1-9</sup> As well as guiding axons at multiple regions in the developing nervous system,<sup>10</sup> Slit/Robo signalling also has non-neuronal roles including in development of lung,<sup>11</sup> kidney and mammary gland.<sup>12-15</sup> Additionally, Slit/Robo signalling can promote and inhibit endothelial cell migration and angiogenesis,<sup>16-19</sup> and is required during heart development with *Robo1/2* mutant mice presenting with partial absence of pericardium, reduced sinus horn myocardium and alignment defects of caval veins.<sup>20</sup> In *Drosophila*, *Slit* acts as a long range chemorepellent to drive the migration of muscle precursor cells away from the midline,<sup>5</sup> and expression of Slit at epidermal muscle attachment sites arrests migration of muscle cells to facilitate correct development of muscle-tendon attachment sites.<sup>21-24</sup> 

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Reflecting their roles during development of multiple tissues, *Slits* and *Robos* are expressed in regions of the developing vertebrate embryo outside the nervous system such as branchial arches, reproductive organs, developing heart and kidney and the limb bud of mouse and chicken embryos, particularly in and around the forming joints and muscle regions.<sup>2,6,9,11,18,25-27</sup> Here we focus on the nature and role of *Slit/Robo* signalling during limb development.

Expression of *Slits* and *Robos* has been reported in developing mouse and chicken limbs, and are grossly comparable.<sup>2,9,26,27</sup> However, there is a disparity in the reported expression of *Slit1* in the developing mouse limb. No expression of *Slit1* was described during mouse limb development by Yuan et al. 1999<sup>9</sup> but was described at E12.5 in posterior and anterior margins and at the digit tips and over the joints at E13.5 by Holmes et al. 1998.<sup>2</sup> Published expression patterns suggest multiple potential roles for Slit-Robo signalling during limb development. For example, central mesenchyme expression patterns of Robos are similar to those of muscle markers<sup>27</sup>, and Slits are expressed in domains of migrating myoblasts,<sup>26,27</sup> though no expression of *Slits* or *Robos* co-localises with differentiating myoblasts.<sup>27</sup> Expression of *Slits* and *Robos* also are detected interdigitally, along digit borders in patterns resembling developing tendons, and in presumptive joint sites.<sup>2,9,26,27</sup> Axon guidance pathways also have been linked to bone development and human joint disorders, and fibroblasts within joints of patients with rheumatoid arthritis show increased Robo3 and decreased Slit3 expression.<sup>28</sup> However, despite analysis of limb expression patterns, the precise roles of Slit/Robo signalling during vertebrate limb development remains unknown.

In this paper, we have analysed *Slit* and *Robo* expression patterns in mouse fore- and hindlimbs and confirm that *Slit1* is not expressed in the developing mouse limb. We utilise *Slit* knockout mice<sup>29,30</sup> to show that knockdown of individual *Slit* genes or *Slit1* and *Slit2* in combination does not impact upon mouse limb development. Limb length and expression patterns of markers for joint, muscle, blood vessel, tendon and nerve development are normal. In contrast, locally inhibiting Slit signalling in the proximo-central region of developing chicken limb buds resulted in a shortening of the length of the humerus. These findings demonstrate that Slit signalling has an essential role incontrolling the length of limb elements.

80 Results

# Slit and Robo expression patterns support a role for Slit-Robo signalling in mouse limb and joint development

To confirm which specific *Slit* and *Robo* family members are expressed in developing mouse limbs, and the temporo-spatial patterns of their expression, we used whole mount in situ hybridisation with mRNA riboprobes against Slit1, Slit2, Slit3 and Robo1, Robo2 and Robo3. Analyses were carried out at E13.5 (the point at which digits become discernible, nerves have entered the hand- and foot-plate and development of muscles starts to be seen), through to E15.5 (distal phalanges have formed, digits have separated and the nerve plexus has reached the fingertips).<sup>31,32</sup> Earlier expression patterns have been mapped in detail previously,<sup>2,9,27</sup> although apparently disparate patterns for *Slit1* and *Slit3* have been reported.<sup>2,9</sup>

In agreement with Yuan et al 1999<sup>9</sup>, no *Slit1* expression was detected in the fore- and hindlimb between E13.5 and E15.5 in whole mount and section images (Figure 1a, a', g, g', m, m', s). In contrast, strong expression of both Slit2 (Figure 1b, b', h, h', n, n', t) and Slit3 (Figure 1c, c', i, l', o, o', u) were detected in both the developing fore- and hind-limbs. In both the fore- and hindlimbs, Slit2 was expressed in the interdigital regions and digit borders at E13.5 through to E14.5, with strongest expression at E13.5 (Figure 1b, b' arrowheads). At E14.5 and E15.5, expression of Slit2 was restricted to the digit borders visible in whole mount and section images (Figure 1h, h' n, n', t arrowhead). In contrast to Slit2, expression of Slit3 intensified through development from E13.5 to E15.5 and was seen in proximal fore- and hind-limb mesenchyme at E13.5 (Figure 1c, c'). At E14.5 and E15.5 Slit3 was expressed along proximal digit borders, with broader regions of expression just proximal to

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101 presumptive joint regions (Figure 1i, i', o, o' arrows), with a weak expression band visible at the distal 102 interphalangeal joint of E15.5 limbs (Figure 1o, o' arrowheads). Sections through the digits 103 demonstrated strong expression of *Slit3* surrounding the digits as well as in mesenchyme ventral to 104 the digits (Figure 1u).

At E13.5, Robo1 was expressed in the hand- and foot-plate, as well as at the metacarpophalangeal/metatarsophalangeal joints (Figure 1d, d' arrowheads). A low level of expression was observed at the proximal interphalangeal joint in the E13.5 forelimb (Figure 1d arrow), however no expression was visible at the proximal interphalangeal joint in the E13.5 hindlimb (Figure 1d'). At E14.5 *Robo1* was expressed in both the hand- and foot-plate, and in the proximal and distal interphalangeal joints (Figure 1j, j'). By E15.5 expression was clearly visible in the metacarpophalangeal/metatarsophalangeal and interphalangeal joints (Figure 1p, p' arrowhead). Sections through the interphalangeal joints at E15.5 demonstrated Robo1 expression around the periphery of the joints (Figure 1v). Robo2 was expressed in the forming cartilage condensations of E13.5 forelimb handplates (Figure 1e). In contrast Robo2 expression in the hindlimb was restricted mainly to the footplate with small regions of expression visible in interdigital regions around digits 1 and 5 (Figure 1e' arrowhead). At E14.5 *Robo2* was visible at the site of the proximal interphalangeal joint. and at the metacarpophalangeal/metatarsophalangeal joints (Figure 1k, k'). By E15.5 Robo2 was expressed at the distal interphalangeal joint as observed in whole mount and section images (Figure q', the borders of the 1q, w arrowheads). Robo2 was expressed at metacarpophalangeal/metatarsophalangeal joints (Figure 1q, q', w arrows). At all ages examined Robo3 was not expressed in the developing mouse limb, confirming previous observations (Figure 1f, f', l, l', r, r', x).<sup>27</sup> 

124 Loss of Slit1 and Slit2 does not affect mouse limb development

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Slits and Robos have been linked to joint disorders such as scoliosis, kyphosis and arthritis.<sup>28,33,34</sup> To investigate if Slit/Robo signalling is essential for normal joint development and maintenance, we analysed fore- and hind-limbs from Slit1<sup>-/-</sup> Slit2<sup>-/-</sup> mouse mutants<sup>30</sup> and control (Slit1<sup>-/-</sup> Slit2<sup>+/+</sup> littermates or wild-type) embryos using markers for joint (Gdf5), connective tissue (Scx), muscle (Myod1), blood vessel (Cdh5) and neuronal development (anti-neurofilament antibody).<sup>32</sup> Because Slit1 and Slit2 can function redundantly<sup>30</sup> and it is potentially possible that our expression analyses may have failed to detect very low levels of *Slit1* in the developing limbs, *Slit2<sup>-/-</sup>* mice were analysed on a Slit1<sup>-/-</sup> background, by breeding Slit1<sup>-/-</sup> Slit2<sup>+/-</sup> mice. We also analysed crosses of Slit1<sup>+/-</sup> mice to confirm loss of *Slit1* alone had no impact on limb development.

As expected, since no expression of *Slit1* was observed in developing limbs, *Slit1<sup>-/-</sup>* fore- and hindlimbs appeared phenotypically normal (Figure 1a, g, m; Figure 2A, B, C). Fore- and hindlimbs of Slit1-/- Slit2-/- mutants also appeared grossly normal and there were no significant differences in the relative length of the forelimbs or hindlimbs of Slit1-/- mutants or Slit1-/- Slit2-/- mutants compared to littermate controls (Slit1<sup>+/+</sup> or Slit1<sup>-/-</sup> Slit2<sup>+/+</sup> respectively; Figure 2A, B). Development of joints, connective tissue, muscle, blood vessels and nerves also appeared similar between wild-type (Slit  $1^{+/+}$ ) and Slit1<sup>-/-</sup> Slit2<sup>-/-</sup> limbs. At E15.5 Gdf5, a marker of joint development, was expressed in carpometacarpal, metacarpophalangeal, proximal (Figure 2C white arrows) and distal interphalangeal joints in wild-type and Slit1<sup>-/-</sup> Slit2<sup>-/-</sup> forelimbs (Figure 2C). Expression of Cdh5, an endothelial cell marker, was observed throughout the upper and lower limb mesenchyme and in the hand-plate up to the proximal interphalangeal joint along the digits in wild-type and Slit1<sup>-/-</sup> Slit2<sup>-/-</sup> limbs. More intense regions of Cdh5 expression were seen interdigitally, at the digit base (Figure 2C black arrows) and avascular regions were normally visible at the digit tips in all genotypes analysed. No obvious differences in expression patterns of Cdh5 were observed between wild type and mutant mice (Figure 2C). At E14.5 expression of Scx (Scleraxis), a marker of developing tendons, was observed as distinct bands of expression in wild-type and Slit  $1^{-/-}$  Slit  $2^{-/-}$  limbs extending along digits from the foot-plate, with expression also seen at developing joint sites (Figure 2C black arrowheads). At E15.5 Myod1,

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which is expressed in muscle fibres, was expressed in the upper limb and in the footplate proximal to the digits in both wild type and *Slit1<sup>-/-</sup>Slit2<sup>-/-</sup>* hindlimbs (Figure 2C).

At E11.5, the patterning of main nerve branches entering the forelimb and hindlimb also were not different between *Slit1<sup>+/+</sup>, Slit1<sup>-/-</sup>* and *Slit1<sup>-/-</sup> Slit2<sup>-/-</sup>* mice (Figure 3a-c arrows, 3a'-c', asterisks). Nerves had progressed along the forelimb and entered the handplate by E13.5 (Figure 3d-f) and progressed to digit tips by E14.5, with no difference in nerve patterning between  $Slit1^{+/+}$ ,  $Slit1^{-/-}$  and *Slit1<sup>-/-</sup> Slit2<sup>-/-</sup>* mice (Figure 3g-i, arrowheads). These findings indicate that at the time points examined early neural patterning appears normal in Slit1-/- and Slit1-/- Slit2-/- mutant mouse limbs. Altogether, these data indicate phenotypically normal limbs in the absence of *Slit1* and *Slit2*. 

#### Development of Slit3 mutant mouse limbs also appeared phenotypically normal

Strong Slit3 expression is seen during mouse limb development, we therefore sought to analyse Slit3<sup>-/-</sup> mouse limbs during development. A comparison of limb size along with whole mount in situ hybridisation analysis of CdhH5 and Myod1 in Slit3<sup>-/-</sup> limbs did not reveal any phenotypic difference between wild type and mutant limbs. There was no difference in limb length between Slit3<sup>+/+</sup> and Slit3<sup>-/-</sup> mice (Figure 4A). At E15.5, in both Slit3<sup>+/+</sup> and Slit3<sup>-/-</sup> forelimbs, Cdh5 was expressed through the handplate with strong expression along the digit borders (Figure 4B). Myod1 was expressed in the proximal limb mesenchyme and in the handplate, with a central band of expression connecting expression regions of the proximal limb and handplate of Slit3+/+ and Slit3-/- limbs (Figure 4B).

#### Robo2-Fc inhibits Slit-signalling

The lack of a mutant phenotype in *Slit1<sup>-/-</sup>Slit2<sup>-/-</sup>* or *Slit3<sup>-/-</sup>* limbs raised the possibility that *Slit2* and Slit3 might function redundantly during limb development. In support of this idea, previous 

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studies have demonstrated that multiple *Slit* alleles are often required to be lost before a phenotype is seen.<sup>20,30,35-37</sup> Moreover, in contrast to *Slit1<sup>-/-</sup>* mice which are viable and fertile, *Slit2<sup>-/-</sup>* pups die perinatally<sup>30</sup>, as do more than 50% of *Slit3<sup>-/-</sup>* mutants.<sup>38</sup> Generation of *Slit2<sup>-/-</sup> Slit3<sup>-/-</sup>* embryos therefore would require breeding of Slit $2^{+/-}$  Slit $3^{+/-}$  mice meaning approximately only 1 in 16 embryos would be double mutants. We therefore sought an alternative approach for knocking down Slit2 and Slit3 signalling in the developing limb.

The ectodomain of Robo2 fused to the Fc domain of human immunoglobulin (Robo2-Fc) forms a soluble inhibitor of Slit activity that binds with high affinity to Slits but, because it lacks the intracellular domain, cannot mediate Slit signalling.<sup>1,39</sup> Robo2-Fc and Robo ectodomains fused to hemagglutinin have been used previously to attenuate the Slit-dependent growth and branching of cortical neurons and the inhibitory effect of the septum on migration of subventricular zone neurons.<sup>39,40</sup> To confirm that Robo2-Fc can attenuate Slit signalling in our hands we cultured E14.5 mouse retinal explants in collagen gels at a short distance (100 - 300 µm) from clusters of approximately 500 293T cells transfected with the vector alone or formed from a 1:1 mixture of control cells and cells transfected with Robo2-Fc, control cells and Slit2-transfected cells or Robo2-Fc-and Slit2-transfected cells (Figure 5A). Slit2 is a potent inhibitor of retinal ganglion cell axon outgrowth, decreasing the number and length of axons that extend from the retinal explants (Fig 5A, C).<sup>41</sup> Robo2-Fc alone had no effect on retinal ganglion cell axon outgrowth but attenuated the inhibitory effect of Slit2 (Figure 5 A, C). To confirm that Robo2-Fc can inhibit endogenous sources of Slit we co-cultured E14.5 mouse retina explants in collagen gels with tissue dissected from the ventral midline of the diencephalon. Slit1 and Slit2 are strongly expressed in the ventral diencephalon<sup>41,42</sup> and, in vitro, ventral diencephalon tissue secretes signals that are inhibitory to retinal ganglion cell axon outgrowth.<sup>43</sup> Seeding the collagen gel with *Robo2*-Fc transfected cells had no effect on the extent of retinal ganglion cell axon outgrowth compared to explants cultured in the presence of control cells (Figure 5B, D), but abrogated the inhibitory effect of ventral diencephalon tissue on axon outgrowth (Figure 5B, D). These findings confirm that Robo2-Fc can be used to inhibit slit signalling. 

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Local inhibition of Slit signalling by implanting *Robo2-Fc* transfected cells into the proximo-central
 region of early chicken embryo forelimb buds decreases the length of the humerus.

204 To investigate the effect of knocking down Slit signalling in the developing limb, we turned to 205 the chicken embryo where we were able to locally inhibit signalling by all Slits by transplanting cells 206 expressing Robo2-Fc into the proximo-central region of the forelimb bud, an area which fate map studies have demonstrated contributes to the humerus.<sup>44</sup> Comparison of *Slit* and *Robo* expression in 207 208 developing mouse and chicken limbs demonstrated grossly similar patterns of expression.<sup>2,9,26,27</sup> 209 However, in contrast to mouse, SLIT1, SLIT2 and SLIT3 are all expressed in the developing chicken limb 210 (Table 1).<sup>26,27</sup> Aggregates of approximately 500 293T cells were grafted into the proximo-central region 211 of HH St21 (E3.5) chicken limbs. To confirm Robo-Fc production by the transfection cells, in each 212 experiment clusters of transfected cells were also embedded in collagen gels and cultured for 24 -72 213 hrs and fixed and stained with anti-human polyvalent immunoglobulins which bind to the Fc domain 214 of the Robo2-Fc protein (Figure 6A). No Robo2-Fc protein was detected in cells transfected with the 215 vector alone at any time point (Figure 6A), but was localised to clusters of cultured Robo2-Fc 216 transfected cells from 0 hrs in vitro (48 hrs after transfection) until at least 72 hrs in vitro (the latest 217 time point analysed; Figure 6A).

218 After grafting at HH St21 (~E3.5), limbs were left to develop to E7. Cartilage stains showed 219 normal limb patterning in grafted limbs, with all cartilage elements present (Figure 6B). However, in 220 limbs grafted with Robo2-Fc transfected cells the humerus was shorter compared to the contralateral 221 unoperated limb (Figure 6B arrowhead, C, D). The ratio of the humerus length in grafted compared to 222 the contralateral unoperated limb was  $0.87 \pm 0.01$  for limbs grafted with *Robo2*-Fc expressing cells 223 compared to 1.00 ± 0.02 for limbs grafted with control cells (p < 0.01; Student's unpaired t-test; Fig 224 6C). No significant difference was found in the relative length of the radius, ulna and digits 1-3 for 225 limbs grafted with control or Robo2-Fc transfected cells (Figure 6B, C). Plotting the data using **Developmental Dynamics** 

estimation graphics, which illustrate effect sizes and their uncertainty,<sup>45,46</sup> confirmed that the relative
 length of the humerus, but not other limb elements, was shorter in *Robo2-Fc* grafted limbs (Fig 6D).
 This specific reduction in humerus length correlates with the proximo-central position of the grafted
 *Robo2-Fc* transfected cells, a region which fate maps have demonstrated gives rise to the humerus.<sup>44</sup>

# 231 Joint and tissue development appears normal in Robo2-Fc grafted chicken limbs.

To determine if other aspects of limb development in addition to the length of the humerus were affected in Robo2-Fc grafted limbs, whole mount in situ hybridisation was performed for markers of joint patterning (GDF5), connective tissue (SCX), muscle (MYOD1) and blood vessels (CDH5). Limbs were examined 24hr and 48hr post-graft. At 48 hours post-graft GDF5 expression was observed in two regions at the proximal mesenchyme, continuing as one band of expression distally to the hand-plate where a larger region was seen anteriorly and a smaller region of expression posteriorly in both Robo2-Fc grafted and contralateral limbs (Figure 7a, b). At HH St27, 48 hrs after grafting, connective tissue has yet to develop extensive patterning and SCX was expressed weakly at regions of metacarpal development in Robo2-Fc grafted and contralateral limbs (Figure 7c, d). MYOD1 was widely expressed in the proximal limb mesenchyme, where expression continued distally to the handplate with weaker expression observed medially through the limb mesenchyme in Robo2-Fc grafted and contralateral limbs 24 hours post-graft (Figure 7e, f). At 48 hours post-graft in Robo2-Fc grafted and contralateral limbs, MYOD1 was expressed in two large regions of proximal mesenchyme, continuing as two narrower lines of expression extending distally along anterior and posterior mesenchyme joining to form a thick region of expression in medial mesenchyme with no expression in the most distal mesenchyme (Figure 7g, h).

Defects in blood vessel development can also influence bone development.<sup>47,48</sup> For example, in *Vegfa*<sup>120/120</sup> mice, which express only the VEGFA<sub>120</sub> isoform, lengths of long bones are reduced.<sup>49,50</sup>

It is unclear whether Slit/Robo signalling acts as an attractant or repellent to endothelial cell migration,<sup>19,51,52</sup> however functioning as an attractant to endothelial cell growth during bone development would explain reduced limb cartilage elements upon neutralisation of Slit signalling. However, vascular networks appeared normal in Robo2-Fc grafted chicken limbs, at least at the time points analysed. At 24 hours post-graft, CDH5 was expressed in capillary networks throughout the limb, with strongest expression observed at a single axial artery in Robo2-Fc grafted and contralateral limbs (Figure 7i, j). At 48 hours post-graft, CDH5 was expressed in capillaries throughout the limb, more strongly expressed at the main axial artery plexus and in vascular rich regions between metacarpals, and absent from the cartilage condensations in Robo2-Fc grafted and contralateral limbs (Figure 7k, I). These findings demonstrate that joint, muscle, tendon and blood vessel development appear normal in Robo2-Fc grafted limbs, at least at early stages post-graft. 

# Cell death is not elevated in Robo2-Fc grafted chicken limbs

We used lysotracker red assay to determine if inhibition of Slit signalling through expression of Robo2-Fc altered cell death. Lysotracker is a dye that is rapidly taken up by lysosomes, and an increase in activity of lysosomes is correlated with increased cell death.<sup>53</sup> Lysotracker was used on limbs fixed 6hr and 24hr post graft (Figure 6A). In contralateral limbs and limbs grafted with control or Robo2-Fc transfected cells 6hr after grafting, lysotracker labelled an area of central, proximal mesenchyme at the cut site, as well as what appeared to be individual cells in a random fashion throughout the limb bud (Figure 8A arrowheads). Grafted cells were also labelled with lysotracker (Figure 8A, arrow). At 24hr post-graft, lysotracker labelled grafted cells in all grafted and contralateral limbs (Figure 8B arrowheads). We also noticed that lysotracker also detected the anterior necrotic zones of grafted and contralateral limbs, and which appeared unchanged in any of the limbs (Figure 8B arrows). Apart from labelling of cell aggregates, lysotracker did not identify areas of increased cell

death following grafting. We conclude that blocking Slit signalling does not elevate cell death in thedeveloping limb.

Together, these results demonstrate that a local reduction in Slit-dependent signalling in the proximo-central region of the developing chicken limb reduces the length of the humerus but, at least in the first 24-48 hours following knockdown of signalling, does not impact on joint development, tissue patterning or cell death.

# 281 Discussion

Previous studies have described expression patterns of Slits and Robos in early mouse embryos. Slit2 is expressed in the distal limb regions in the presumptive hand/footplate at E11.5 and *Slit3* in the proximal posterior region and distal anterior mesenchyme. At E12.5 *Slit2* is strongly expressed in interdigital regions, and expression fades as apoptosis takes place to separate digits.<sup>2,9</sup> No expression of *Slit1* was described during mouse limb development by Yuan et al. 1999<sup>9</sup> but was described at E12.5 in posterior and anterior margins and at the digit tips and over the joints at E13.5 by Holmes et al. 1998.<sup>2</sup> Robo1 and Robo2 are detected in proximal and central mesenchyme, respectively, at E11.5.<sup>9,27</sup> At E15.5 Robo1 is expressed at regions along the digits resembling presumptive joint sites, suggesting a possible role in joint development, Robo2 is expressed at digit tips and proximal digit regions and Robo3 is not expressed during limb development (Table 1).<sup>27</sup> 

In this paper, expression analysis of *Slits* and *Robos* during mouse fore- and hind-limb development demonstrated no expression of *Slit1*, in apparent conflict with Holmes et al. 1998.<sup>2</sup> A comparison of sequencing results reveals different nomenclature systems were implemented by Holmes et al. 1998<sup>2</sup> and Itoh et al. 1998<sup>4</sup> when vertebrate Slits were originally cloned: *Slit1* described by Holmes et al. 1998 refers to the *Slit3* described by Itoh et al. 1998 and Yuan et al. 1999.<sup>2,4,9</sup> The current official nomenclature of the mouse *Slit* genes follows the naming system adopted by Itoh et Page 13 of 38

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al. 1998.<sup>4</sup> Consequently, the current official name for the mouse *Slit1* gene described in Holmes et al. 1998<sup>2</sup> is *Slit3*. Our findings therefore are in agreement with both Holmes et al, 1998<sup>2</sup> and Yuan et al, 1999,<sup>9</sup> demonstrating strong expression of *Slit2* and *Slit3*, but not *Slit1*, in the developing mouse limb. Phenotypically normal Slit1-<sup>-/-</sup>, Slit2-<sup>-/-</sup> compound mutants and Slit3-<sup>-/-</sup> single mutant mouse limbs may be due to functional redundancy between Slits. Defects seen in *Slit* mutants are more profound when more than one *Slit* or *Robo* allele is disrupted, and often multiple genes are required to be lost before a phenotype is seen. For example, commissural axon guidance defects are see at the floorplate only in triple *Slit1<sup>-/-</sup>Slit3<sup>-/-</sup>* mice.<sup>36</sup> Although subtle axon guidance defects are seen in single *Slit1<sup>-</sup>* /- and Slit2-/- mutants at the optic chiasm, defects are substantially more severe in Slit1-/-Slit2-/- mice.<sup>30</sup> Moreover, previous studies have demonstrated that functional redundancy between Slits also can occur despite distinct expression patterns. For example, at the optic chiasm severe axon guidance defects are only observed in double Slit1/2 mutant mice despite complementary, non-overlapping expression of *Slit1* and *Slit2* in the ventral diencephalon.<sup>30,41,42</sup> This could also be the case during mouse limb development, where at E14.5 and E15.5 Slit2 is expressed interdigitally and Slit3 in adjacent regions of proximal digit borders.

Following grafting of Robo2-Fc transfected cells into the proximo-central region of the developing chicken limb the length of the humerus but not other limb elements was affected. The most parsimonious explanation for the specific effect on the humerus is that it reflects the site at which the cells were grafted into the HH St21 forelimb bud combined with limited diffusion within the tissue of the Robo2-Fc generated by the transfected cells (Figure 8C). From Dil labelling fate maps cells in the proximo-central part of the developing limb remain where they are and end up in the humerus and elbow region.<sup>44</sup> Thus, influence of Robo2-Fc will likely be localised to the developing humerus. Unfortunately attempts to determine the extent of Robo2-Fc diffusion within the limb bud were not successful. Nevertheless, our results are consistent with a relatively local site of action. Future experiments using methods that enable more widespread expression of Robo2-Fc within the

developing limb will be required to determine if inhibiting Slit signalling throughout the limb bud affects the development of other limb cartilage elements. However, the Robo2-Fc construct is too large to insert into the RCAS viral vector commonly used for driving gene expression in chicken embryos.

A decrease in the length of the humerus could result from increased cell death, and/or an effect on bone, blood vessel, and/or neural development. However, lysotracker staining showed no change in cell death patterns in the limb. It is unclear whether Robo1 or Robo2 are expressed in chondrocytes. However, *Slit2* is reported to be expressed in periosteal cells and *Slit3* in both periosteal cells and proliferating chondrocytes in HH St30 chicken hindlimb.<sup>26</sup> Slit2, Robo1 and Robo2 are expressed during differentiation of rat osteoblasts in vitro and Slit2 acts as an inhibitor to osteoblast differentiation.<sup>54</sup> Slit3 is secreted by osteoclasts, promotes osteoblast migration and suppresses osteoclast differentiation.<sup>55,56</sup> Only deletion of osteoclast-specific *Slit3*, as opposed to osteoblast- or neuron-specific deletion, resulted in a reduction in bone mass.<sup>56</sup> Blood vessel development also appeared normal in limbs grafted with Robo2-Fc transfected cells. Further experiments therefore will be required to determine the mechanisms by which inhibiting Slit-signalling decreases the length of the humerus. 

In conclusion, our functional experiments have demonstrated a role for Slit-Robo signalling in determining bone length, supporting a role for Slit-Robo signalling in bone development and/or homeostasis. Furthermore, a role for Slit-Robo signalling in joint homeostasis is supported by our expression pattern data showing *Slit3, Robo1* and *Robo2* in developing joint regions.

- 344 Experimental Procedures
- 56 345 <u>Animals</u>

All experimental procedures and conditions were in accordance with Institutional and the UK Animals (Scientific procedures) Act 1986 and associated Home Office guidelines. Fertilised White Leghorn chicken eggs were purchased from Henry Stewart, Norfolk, UK and incubated at 37°C to the desired developmental timepoint and staged according to Hamburger and Hamilton (1951).<sup>57</sup> The following mouse strains were used: C57BL/6J wild-type mice, Slit1 and Slit2 single and compound mutants on a mixed C57/BL/6J;129/Sv background and Slit3 mutant mice on a C57BL/6J background.<sup>29,30,58</sup> Mice were mated and noon on the day of cervical plug formation counted as E0.5. Pregnant mothers were killed by cervical dislocation and the embryos either fixed in 4% formaldehyde in PBS (PFA) or tissue dissected and used for culture experiments or processed immediately for RNA extraction. Genotyping protocols are available on request. 

# 356 Generation of riboprobes

To generate riboprobes for mSlit3 and cGDF5 RNA was extracted from embryonic tissues using the Qiagen RNeasy Kit and cDNA synthesised using SuperScript II (ThermoFisher Scientific) following the manufacturers' instructions. DNA fragments were amplified by PCR (94°C for 5 min, 35 cycles of 94°C for 40s, 55°C for 1 min, 72°C for 90 s followed by a final extension at 72°C) and ligated into either pGEM T-Easy (Promega; mSlit3) or pBlueScript KS(+) (cGDF5). For mSlit3 a 1:1 mixture of E14.5 and E15.5 mouse limb cDNA was used in the PCR, for cGDF5 a 1:1 mixture of HH St20 (E3) and HH St25 (E5) chicken cDNA was used. The following primers were used: mSlit3 F: AGCGAAAACCAGATCCAGGG R: TGGCAGTCGCAAACAAATGG; cGDF5 F: GGTGACTCCAAAGGTCCCAA R: CAGTCCTGAGATCAACCGCT. The ligated plasmids were sequenced (DNA Sequencing and Services, University of Dundee) to confirm the identity and orientation of the inserted DNA. Other probes used were: mouse Cdh5, Gdf5, Myod1<sup>32</sup>; Robo1, Robo2, Robo3, Slit1, Slit2 (Dr Tessier-Lavigne, The Rockefeller University)<sup>1,41</sup>; Scx<sup>59</sup> and chicken SCX (Dr Ronen Schweitzer, Oregon Health & Science University)<sup>60</sup>; MYOD1 (Prof Ed Laufer, Columbia University)<sup>61</sup>; CDH5 (Dr Jaffredo, Sorbonne University)<sup>62</sup>. Identity of all probe templates was

370 confirmed using sequencing (Table 2). In vitro transcription using DIG-labelled nucleotides (Sigma
 371 Aldrich) was used to generate antisense riboprobes.

# 372 <u>Whole mount in situ hybridisation</u>

Whole mount in situ hybridisation was performed on mouse and chicken embryos as described previously.<sup>27</sup> Briefly, embryos were fixed overnight in 4% PFA and dehydrated in three washes each of 50% and 100% methanol in PBT (PBS + 0.1% Tween-20) before bleaching in 6% H<sub>2</sub>O<sub>2</sub> (Sigma Aldrich) in PBT, rehydration washes in 75%, 50% and 25% methanol in PBT and treatment with Proteinase K for 15 minutes (20mg/ml for mouse E13.5, E14.5 and chicken HH St 20-30; 30mg/ml for chicken HH St 30+; 40mg/ml for mouse E15.5). Embryos were post fixed in 4% PFA, washed in hybridisation solution (50% formamide, 5x SSC pH 4.5, 50µg/ml Heparin, 50µg/ml tRNA, 1% SDS) and incubated with required probe diluted 1:100 in hybridisation solution overnight at 65°C. The embryos were washed 3 times with Solution 1 (50% formamide, 5x SSC pH 4.5, 1% SDS) at 65°C, 3 times with Solution 3 (50% formamide, 5x SSC pH 4.5) at 60°C, followed by 3 washes with TBST (TBS + 1% Tween-20). The embryos were incubated for 60 min in 10% sheep serum in TBST before overnight incubation in anti-DIG-AP Fab fragments (Sigma Aldrich 11093274910; 1:5000 in 1% sheep serum in TBST). The embryos were washed for 24 hours in TBST before washes in NTMT (to make 100ml: 2ml 5M NaCl + 10ml 1M Tris-HCl (pH 9.5) + 5ml 1M MgCl<sub>2</sub> + 1ml Tween-20 + 82ml H<sub>2</sub>O) and incubation at room temperature in colour solution (NTMT + BCIP (50mg/ml; 3.5µl per 1ml NTMT) + NBT (75mg/ml; 4.5µl per 1ml NTMT)). Colour reaction was terminated by several washes in PBS. For each gene and time point, analyses were performed on a minimum of 4 embryos.

## 390 Anti-neurofilament staining

Signal Whole mount antibody staining was performed on mouse embryos as described previously.<sup>26,57</sup>
 Briefly, tissue was fixed in 4% PFA overnight at 4°C, transferred to Dent's bleach (33.3% H<sub>2</sub>O<sub>2</sub>; 66.6%
 Dent's fix) for 24 hours, washed in methanol and fixed in Dent's fix (20% DMSO, 80% methanol) for 24
 hours. The tissue was washed in PBS and placed in blocking buffer (75% PBS, 20% DMSO, 5% goat

serum) for 1 hour at room temperature before incubation with anti-neurofilament antibody (Millipore
AB1987; 1:50 in blocking buffer) for 24 hours at 4°C. The tissue was washed several times in PBS before
incubation with Cy3-conjugated goat anti-rabbit IgG (Jackson ImmunoResearch; 1:1000 in blocking
buffer) overnight at 4°C. The tissue was washed several times in PBS followed by 100% methanol and
imaged and cleared in benzoic acid benzyl benzoate (BABB). For each genotype and time point,
analyses were performed on 2 embryos.

# 401 <u>Transfection of 293T cells and formation of cell aggregates</u>

293T cells were cultured in DMEM/10% foetal calf serum/penicillin/streptomycin to 70 % confluency in 60 mm plates and transfected with the empty vector or a plasmid encoding Robo2-Fc (gift Dr Marc Tessier-Lavigne; Rockefeller University)<sup>1</sup>, or Slit2 fused at its C terminus with a myc-tag (gift Dr Marc Tessier-Lavigne; Rockefeller University)<sup>1,41</sup> using Lipofectamine 3000 (ThermoFisher Scientific) according to the manufacturer's instructions. After 24 hrs, the cells were detached from the plates using trypsin (ThermoFisher Scientific) and resuspended at a density of 25 cells/µl in fresh culture medium. To generate clusters composed of a 1:1 ratio of Robo2-Fc, Slit2 or vector transfected cells, following resuspension, the cells were mixed such that the final volume contained 50% of each cell type at density of 25 cells/ $\mu$ l. Drops of cells (20  $\mu$ l) were aliguoted onto the inside of a lid of a sterile 90mm dish, the lid replaced on the dish and cultured for 48 hours to form aggregates of ~500 cells.

# 412 <u>Collagen gel cultures of cell aggregates</u>

413 Collagen gel cultures were prepared as described previously.<sup>41,63</sup> A 1:1 mix of bovine dermis collagen
413 (VWR 392-2502) and rat tail collagen (VWR 734-1097) was prepared, and 10x DMEM and 0.8M
414 (VWR 392-2502) and rat tail collagen (VWR 734-1097) was prepared, and 10x DMEM and 0.8M
415 NaHCO<sub>3</sub> added (enough to make the mixture light pink). Collagen (20 µl) was added to the centre of
416 each well of a 4-well plate (Nunc) and left to set for 20 minutes at 37°C before cell aggregates were
417 pipetted on top and covered in 20 µl collagen. Cultured cell aggregates were fixed in 4% PFA at 0, 24,
418 and 72 hours in vitro before PBS washes and blocking for 90 minutes with 10% goat serum, 0.2%
419 Triton X-100 in PBS at room temperature. Cultures were incubated with FITC conjugated anti-human

polyvalent immunoglobulins (Sigma F-6506; 1:200 in blocking buffer) overnight (to detect the Fc
portion of the Robo2-Fc construct) or in anti-myc (Developmental Studies Hybridoma Bank 9E10; 1:9
in blocking buffer) followed by Cy3-conjugated goat anti-mouse IgG (Jackson immunoresearch 1:2000
in 1% goat serum/PBS; to detect myc-tagged Slit2 protein).

424 <u>Retinal explant culture experiments</u>

Peripheral retina from E14.5 wild-type C57BL/6J mice were cultured in a 1:1 mixture of bovine dermis collagen (VWR 392-2502) and rat tail collagen (VWR 734-1097) as described previously<sup>41,63</sup>. For analysis of the effect of Slit2 and Robo2-Fc on axon outgrowth, explants were cultured 100 – 300 μm from clusters of ~500 293T cells composed of control cells transfected with the vector alone or 1:1 mixtures of control cells and Robo2-Fc transfected cells, control cells and Slit2 transfected cells or Robo2-Fc and Slit2 transfected cells. For analysis of the effect of Robo2-Fc on co-cultures of retina and ventral diencephalon tissue, the collagen mixture used to form the bottom layer of the collagen gel was seeded with control or *Robo2-Fc* transfected cells (3000 cells/µl; 60 000 cells/well). Explants were dissected from the ventral midline of the diencephalon as described previously<sup>43</sup> and co-cultured 100  $-300 \ \mu m$  from retinal explants in the collagen/cell mixture. The culture medium was composed of DMEM/F12 containing penicillin/streptomycin and ITS supplement (Sigma Aldrich). After 24 hrs the cultures were fixed and stained with anti-neuron-specific  $\beta$ -tubulin (Sigma Aldrich T8660; 1:500 in 10% goat serum/0.2% triton/PBS) followed by Cy-3 conjugated goat anti-mouse IgG (Jackson Immunoresearch; 1:2000 in 1% goat serum/PBS). The cultures were photographed using a Nikon SMZ1500 microscope and DXM1200 camera and the area covered by the RGC axons quantified using Image J (https://imagej.net/Welcome) as described<sup>41,63</sup>. Briefly, the retinal explant body was deleted from the image, the image was thresholded and converted to binary mode and the number of black pixels corresponding to the retinal axons quantified. The area of each retinal explant also was measured to ensure that differences in explant size did not impact on the results. Data are the mean from 3 independent experiments. 

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# 445 Forelimb surgical grafting experiments

A small window was made in the eggshell and the membranes covering the embryo removed. The 446 upper-facing forelimb of Hamburger and Hamilton (HH) Stage (St) 21 embryo (approximately day 3.5 447 448 of development) was cut in the middle of the limb bud in an anterior to posterior orientation using a 449 surgical blade (Altomed A10136). Aggregates of control (vector-transfected) cells or Robo2-Fc 450 transfected cells were grafted into the forelimb cut. Only embryos with a single, stably inserted cell 451 aggregate were used in analysis. Embryos were fixed 6hr, 24hr or 48hr after manipulation for 452 expression analyses or at E7 (~ 4 days after manipulation) for cartilage staining. The contralateral limb 453 was left un-operated to serve as a control.

# 454 <u>Cartilage staining</u>

E7 embryos were removed from the egg and fixed in 5% TCA overnight. The following day embryos
were placed in to 0.1% Alcian blue for 24 hours, followed by 1% acid ethanol for 24 hours. The embryos
were dehydrated in 3 washes of 100% ethanol and cleared and imaged in methyl salicylate (Sigma
Aldrich). Limb cartilage elements were measured in Image J (https://imagej.net/Welcome). Results
are from 7 independent experiments.

## 460 <u>Cell death analysis</u>

Chick limbs were dissected from the embryo 6 hrs and 24 hrs after grafting and placed in 12 well plates
containing 2ml PBS/well. Lysotracker red (ThermoFisher Scientific; 25 µl) was diluted in 2ml PBS, 1.5ml
PBS removed from each well and 200µl diluted lysotracker added. The plate was incubated, in the
dark, at 37°C for 30 minutes. Limbs were washed 5x in PBS and fixed overnight in 4% PFA at 4°C. Limbs
were rinsed with PBS and dehydrated by washes in 25%, 50% and 100% methanol. Tissue was stored
and imaged in 100% methanol. For each time point analyses were performed on a minimum of 2
embryos.

9 468 <u>Imaging</u>

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Whole mount images were captured using a Nikon SMZ1500 microscope with Nikon DS-L1 camera,
section images using a Zeiss Axiophot microscope with a Nikon DXM1200 camera and whole mount

471 antibody stains and collagen gel culture images using a Nikon SMZ1500 and a Nikon DXM1200 camera.

# 472 <u>Statistical analysis</u>

For null hypothesis significance testing, a Shapiro-Wilk test was used to confirm the data was normally
distributed. Comparison of retinal explants cultured with transfected cells or diencephalon tissue, and
lengths of the limbs in *Slit3* mutant mice was made using ANOVA with TUKEY post-hoc comparison.
For comparison of the lengths of cartilage elements in chicken embryo limbs grafted with control or *Robo2-Fc* an unpaired student's t-test was used. Estimation graphics were generated using DABEST

478 (data-analysis with bootstrap coupled estimation; <u>https://www.estimationstats.com</u>).<sup>45,46</sup>

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484 Data accessibility

485 Data supporting the findings of this study are available within the article or are available from

- 7 486 corresponding authors upon reasonable request.
- 488 **Conflicts of Interest**
- 489 Authors declare no conflicts of interest

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45	673	Figure 2	L. Expression of <i>Slit1, Slit2, Slit3, Robo1, Robo2</i> and <i>Robo3</i> during mouse limb development.			
46						
47	674	(a-r') W	hole-mount <i>in situ</i> hybridisation with probes specific for Slit1 (a, a', g, g', m, m'), Slit2 (b, b', h,			
48						
49	675	h'. n. n'	). <i>Slit3</i> (c. c'. i, i'. o. o'). <i>Robo1</i> (d. d'. i, i'. p. p'). <i>Robo2</i> (e. e'. k. k'. g. g') and <i>Robo3</i> (f. f'. l. l'. r.			
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51	676	r') at E	12.5 $(a-f')$ E14.5 $(g-f')$ E15.5 $(m-r')$ in forelimbs (EL) and hindlimbs (HL) dorsal view $(c,v)$			
52 52	070	i j at L				
55 57	<b>C77</b>	Transis	and an			
55	6//	Transve	nsverse sections through E15.5 foreiimb digits stained by whole-mount in situ hybridisation for			
56		<u></u>				
57	6/8	SIIt1 (s)	i, SIITZ (T), SIIT3 (U), RODOI (V), RODO2 (W) and RODO3 (X). Arrowheads in (b, b', t) indicate			
58						
59	679	express	ion of <i>Slit2</i> in interdigital mesenchyme, arrows in (i, i', o, o') indicate broader regions of <i>Slit3</i>			
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expression along digit borders prior to developing joint sites, arrowheads in (o, o') indicate *Slit3*expression in distal interphalangeal joints., arrowheads in (d, d') indicate *Robo1* expression in cartilage
condensations, arrow in (d) indicates expression in the forelimb proximal interphalangeal joint,
arrowheads in (p, p') indicate *Robo1* expression in developing joint regions, arrowhead in (e) indicates *Robo2* expression in forelimb chondrogenic condensations, arrows in (q, q', w) indicate *Robo2*expression around developing joints, and arrowheads in (q, q', w) indicate expression at the distal
interphalangeal joint. FL: forelimb, HL: hindlimb. Scale bars, 500 µm.

Figure 2. Length and patterning of limb elements is normal in Slit1/2 mutant mice. (A, B) Relative lengths of E15.5 Slit1-/- compared to Slit1+/+ littermate and Slit1-/- Slit2-/- compared to Slit1-/- Slit2+/+ littermate forelimbs (A) and hindlimbs (B). Numbers analysed: Slit1<sup>-/-</sup> n = 3; Slit1<sup>+/+</sup> n = 4; Slit1<sup>-/-</sup> Slit2<sup>-/-</sup> n = 5; Slit1<sup>-/-</sup> Slit2<sup>+/+</sup> n = 4. (C) Whole mount *in-situ* hybridisation for Gdf5 and Cdh5 in E15.5 forelimbs (FL), for Scx in E14.5 forelimbs and for Myod1 in E15.5 hindlimbs (HL) of Slit1+/+ and Slit1-/-Slit2-/- mice, dorsal view. White arrows indicate *Gdf5* expression in proximal interphalangeal joints, black arrows Cdh5 expression at developing interzones and black arrowheads Scx expression at developing proximal interphalangeal joints. Scale bars, 500µm. 

695Figure 3. Nerve patterning is normal in *Slit1/2* mutant mice. Anti-neurofilament staining of696developing nerves in E11.5 forelimbs (FL; a-c) and hindlimbs (HL; a'-c'), E13.5 forelimbs (d-f) and E14.5697forelimbs (g-i) of *Slit1+/+* (a, a', d, g), *Slit1-/-* (b, b', e, h) and *Slit1-/-Slit2-/-* (c, c', f, i) mice. White arrows698indicate nerves entering the forelimbs at E11.5, white asterisks two main nerve branches entering the699E11.5 hindlimbs, and white arrowheads distal development of nerves in E14.5 forelimbs. Scale bars,700500 µm.

Figure 4. *Slit3* mutant mouse limbs appear phenotypically normal. (A) Mean (± s. d.) hindlimb lengths
of E15.5 *Slit3<sup>+/+</sup>*, *Slit3<sup>+/-</sup>* and *Slit3<sup>-/-</sup>* mice. ns: not significant. ANOVA with TUKEY post-hoc comparison.
Numbers on bars indicate numbers analysed. (B) Whole mount *in-situ* hybridisation for *Cdh5* and *Myod1* in E15.5 forelimbs (FL) of *Slit3<sup>+/+</sup>* and *Slit3<sup>-/-</sup>* mice. Scale bars, 500µm.

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706	Figure 5. Robo2-Fc inhibits Slit signalling. (A) Representative examples of retinal explants co-cultured
707	in collagen gels at a short distance (100 – 300 $\mu$ m) from clusters of control 293T cells transfected with
708	the vector alone or 1:1 mixtures of control and Robo2-Fc transfected cells, control and Slit2
709	transfected cells or Slit2 and Robo2-Fc transfected cells. The cultures were fixed after 24 hrs and
710	stained with antibodies against neuron-specific $\beta$ -tubulin to label the retinal ganglion cell axons.
711	Inserts show representative examples of cell clusters stained with anti-human polyvalent
712	immunoglobulins (green) to label the Robo2-Fc produced by the transfected cells and anti-myc (red)
713	to label the myc-tagged Slit2 protein produced by the transfected cells. (B) Representative examples
714	of retinal explants cultured in the presence and absence of ventral diencephalon (dienceph) tissue in
715	collagen gels seeded with control 293T cells transfected with the vector alone or transfected with
716	<i>Robo2-Fc.</i> The cultures were fixed after 24 hrs and stained with antibodies against neuron-specific $\beta$ -
717	tubulin to label the retinal ganglion cell axons. Inserts show representative examples of control and
718	Robo2-Fc transfected 293T cells within the collagen gels stained with anti-human polyvalent
719	immunoglobulins (green) to label the Robo2-Fc produced by the transfected cells. (C) Mean (± s.e.m.)
720	area covered by the retinal ganglion cell axons from retinal explants cultured in the presence of
721	clusters of control cells transfected with the vector alone or formed from 1:1 mixtures of control and
722	Robo2-Fc transfected cells, control and Slit2 transfected cells or Slit2 and Robo2-Fc transfected cells.
723	(D) Mean (± s.e.m.) area covered by RGC axons from retinal explants cultured in collagen gels seeded
724	with control or <i>Robo2</i> -Fc transfected cells in the presence or absence of ventral diencephalon tissue.
725	Numbers on bars indicate number of explants analysed. Data are from 3 independent experiments.
726	** = p < 0.01, * = p < 0.05; ANOVA with TUKEY post-hoc comparison. Scale bars, 200 $\mu$ m.

Figure 6. Local suppression of Slit signalling in the proximo-central region of developing chicken
 limbs decreases the length of the humerus. (A) Representative examples of clusters of 293T cells
 transfected with the vector alone (control) or transfected with *Robo2-Fc* and fixed and stained with

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#### **Developmental Dynamics**

antibodies against the Fc domain at Ohr (time of culturing in collagen; 48 hrs after transfection), 24hr, 48hr and 72hr after culturing in collagen. Scale bars, 200 μm. (B) Cartilage stains of contralateral control (unoperated) chicken limbs and limbs grafted at HH St21 (~E3.5) with clusters of control 293T cells transfected with the vector alone or transfected with *Robo2-Fc* and fixed at E7. White arrow, points to shortened humerus in limbs following graft of *Robo2-Fc* transfected cells. H, humerus, R, radius, U, ulna, D1, digit 1, D2, Digit2, D3, Digit3. Scale bars, 500 μm. (C) Mean (± s.e.m.) relative length of the humerus, radius, ulna, Digit 1, Digit 2 and Digit 3 of limbs grafted with clusters of control 293T cells transfected with the vector alone (white bars) or transfected with Robo2-Fc (grey bars) expressed as a ratio of the length in the contralateral (unoperated) limb. \*\*\* = p < 0.001 compared to limbs grafted with the control cells; Student's unpaired t-test. Numbers on bars indicate number of embryos analysed. (D) Cumming Estimation plots showing the mean difference for the relative length in of the humerus, radius, ulna, Digit 1, Digit 2, and Digit 3 for limbs grafted with control cells transfected with the vector alone or *Robo2-Fc* transfected cells. Data are expressed as the ratio of the limb element length in the grafted: contralateral unoperated limb. The raw data is plotted on the upper axes and each mean difference is plotted on the lower axes as a bootstrap sampling distribution. Mean differences are indicated on the lower plots by the dots and the 95% confidence intervals by the ends of the vertical error bars. The unpaired mean difference between the length of the humerus in limbs grafted with control versus Robo2-Fc transfected cells is 0.124 [95% CI -0.168 lower limit, -0.0938 upper limit]. The p value of the two-sided permutation t-test is 0.0. All other comparisons are not significant (radius, p = 0.109; ulna, p = 0.542 Digit 1, p = 0.899; Digit 2, p = 0.553; Digit 3, p = 0.315). Figure 7. Skeletal and tissue elements appear normal in chicken limbs grafted with Robo2-Fc. (a-l)

Whole mount *in situ* hybridisation for *GDF5* (a, b), *SCX* (c, d), *MYOD1* (e-h) and *CDH5* (i-l) 24hr (e, f, I,
j) and 48hr (a-d, g, h, k, l) after grafting at HH St21 with *Robo2-Fc* transfected cells and in the
contralateral control (unoperated) limb. Arrowheads in (a, b) indicate proximal regions of *GDF5*expression, arrows in (a, b) distal regions of *GDF5* expression, arrows in (c, d) *SCX* expression at regions
of metacarpal development, arrows in (e, f) weak *MYOD1* expression in central mesenchyme, arrows

in (g, h) a single expression domain of MYOD1 in distal mesenchyme, arrows in (I, j) strong expression

Figure 8. Cell death is not elevated in grafted limbs. (A, B) Lysotracker red cell death staining on

contralateral (unoperated) chicken embryo limbs and limbs 6hr (A) and 24hr (B) after grafting with

clusters of control cells transfected with the vector alone or cells transfected with Robo2-Fc. Arrows

in (A) and (B) indicate lysotracker labelling of grafted cells, arrowheads in (A) lysotracker labelling of

proximal central mesenchyme, and arrowheads in (B) lysotracker labelling of anterior necrotic zones.

Scale bars, 500µm. (C) schematic diagrams showing location of grafted cells immediately after grafting

of *CDH5* at the position of the axial artery. Scale bars, 500  $\mu$ m.

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at HH St21 and 24 hours later.

1 ว						
2 3 4	767	Tables				
5 6	768	Table 1. Co	omparisons of expres	sion patterns of Slit	ts and Robos during chick	ken and mouse embryo
7 8	769	limb develo	opment.			
9 10 11 12 12		Gene	Chicken Developmental Stage	Equivalent mouse developmental stage	Expression in chicken limbs*	Expression in mouse limbs
13		Slit1			Around digit tip	Not detected
14		Slit2		E12.5	Deridicital	Interdigital
15		SIIL2				Drewinsel
17		51113		E13.5		Proximal
18 19		Robo1	HH St28	E13.5	Distal mesenchyme, bordering AER	Developing joints
20 21 22 23		Robo1	HH St32	E14.5	Digit tips and digit border	Along each digit at sites of developing joints
23 24 25 26 27		Robo1	HH St36	E15.5	Digit tips, dominas along each digit at sites of developing joints	Along each digit at sites of developing joints
28 29 30		Robo2	HH St28	E13.5	Proximal peridigital mesenchyme	Proximal digit and peridigital mesenchyme
31 32 33 34		Robo2	HH St32	E14.5	Interdigital mesenchyme, digit borders	Proximal mesenchyme around sites of developing joints
35 36		Robo2	HH St36	E15.5	Peridigital, digit tips	Around developing joints, digit tips,
37		Robo3			Not detected	Not detected
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# 772 <u>Table 2 Sequences of Riboprobe Templates</u>

	1			
<u>Gene</u>	<u>Species</u>	<u>Sequence ID:</u>	<u>Nucleotides</u>	<u>Reference</u>
Cdh5	Mouse	NM_009868.4	1671 – 2383	32
CDH5	Chicken	XM_015292499.2	629 – 1679	62
(VE-Cadherin)		_		
Gdf5	Mouse	NM_008109.3	916 – 1748	32
GDF5	Chicken	NM_204338.1	354 – 976	This paper
Myod1	Mouse	NM_010866.2	324 – 805	32
Robo1	Rat*	NM 022188.1	173 – 1075	1
	(mouse)	(NM 0194132.2)	(938 – 1947;	
			92% identity)	
Robo2	Rat*	NM 032106.3	<2095 - 3331	1
	(mouse)	(NM_001358493.1)	<1622 – 2858;	
		/	93% identity)+	
Robo3 (Rig-1)	Mouse	AF060570.1	<4339 - 4580+	64
Scx	Mouse	NM_198885.3	188 – 999	59
SCX	Chicken	NM_204253.1	668 – 1133	60
Slit1	Rat*	NM 022953.2	2515 – 3261	1
	(mouse)	(NM 105748.3)	(2804 – 3550;	
			95% identity)	
Slit2	Rat*	NM_022632.2	<3830 - 5109	1
	(mouse)	(NM_001291227.2)	<5247- 6515;	
	. ,		94% identity)+	
Slit3	Mouse	NM_011412.3	480 - 1390	This paper

\* *Robo1, Robo2, Slit1, Slit2* probe templates were cloned from rat. Sequences recognised in mouse and % identity of probes to these regions in mouse also are given.

\*Sequences for *Robo2, Robo3* and *Robo3* riboprobe templates are longer than given
in the table (*Robo2* ~1.7kb; *Slit2* ~ 1.6kb; *Robo3* ~1.2kb)



Figure 1



Figure 2



Figure 3



Figure 4

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Figure 5



Figure 6



Figure 7



Figure 8

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